1. System displays ready screen
2. User presses the Start Driving button
3. System begins wireless connections
   1. Initialize video stream sockets
   2. Initialize sensor stream socket
   3. Initialize controller stream socket
4. System begins camera stream
   1. Initialize Oculus Rift manager objects
   2. Create OculusState object
   3. Send startCameras signal to the Jetson system
   4. Jetson system starts the camera capture feeds
   5. Jetson system extracts the pixel map
   6. Jetson system sends the video data to the System
   7. System processes the video feed set
   8. System displays feed to the Oculus
5. System begins controller stream
   1. System tells Jetson system to receive controller data
   2. Jetson system begins receiving controller data
   3. Jetson system converts controller data to RC control values
   4. System continues asynchronously polling the controller for a new state
6. System begins sensor stream
   1. System tells Jetson to begin sending sensor data
   2. Jetson sends sensor data
   3. System receives sensor data
   4. System processes sensor data
   5. System continues asynchronously receiving sensor data and processes it
7. System prompts user to put on Oculus Rift headset
   1. System begins displaying processed video data on the Oculus Rift device
8. User puts on Oculus Rift headset
9. System prompts user ready to drive
10. User begins driving RC